

Low voltage AC drives

ABB drives for water and wastewater ACQ810 0.37 to 500 kW



The intelligent drive choice for water and wastewater applications





The ACQ810 drive for water and wastewater applications features tailor made functions for single and multipump system control. These pump specific functions help reduce total life cycle operating and maintenance costs across the pumping system. The drives achieve this by:

- Reducing startup stress on the pump system
- Calculating the required motor speed based current process conditions
- Optimizing energy consumption in parallel pumping systems
- Sharing operating times across pumps
- Monitoring, preventing and scheduling automated pump cleaning runs
- Preventing cavitation and pump dry run
- Providing redundancy in parallel pump systems
- Monitoring energy consumption
- Monitoring and protecting the pump's motor
- Displaying energy saving information in kWh, currency or CO₂ emissions

Optimal pump control for various applications

- Raw water pumps, booster pumps, wastewater pumps
- Rain water pumps, irrigation pumps, slurry pumps
- Submersible pumps, dry-installed pumps

Intelligent solution for controlling pump performance

- Tailor-made pump control functions for single and multipump applications
- Clear, easy-to-understand documentation and software
- Compliance with mandatory EN 61000-3-12 standard on harmonic currents
- Advanced energy saving functions

Easy and cost-effective cabinet assembly

- Fast and easy installation
- Narrow, compact design
- Side-by-side installation saves space
- Modular structure provides flexibility in system design and configuration

Rapid and simple pumping system startup

- Intelligent startup assistant ensures simple pumping system commissioning
- Easy-to-use documentation based on real pumping applications
- Preprogrammed and preconfigured macros for typical pump applications



Advanced energy efficiency in pumping systems

- Energy savings up to 50 percent in speed controlled pump applications – save energy and reduce carbon dioxide emissions
- Advanced functions such as energy optimizer to improve energy efficiency
- Optimized energy consumption in parallel pumping systems
- Easy energy efficiency management built-in calculator monitors used and saved energy and displays them in kWh, currency (\$ or €) or volume of CO₂ emission

Maximized process uptime

- Maintenance assistant handles preventive maintenance for drive and pump, reminding users about planned maintenance based on running hours
- Diagnostic assistant helps to locate problems or reasons for performance changes in pumping system and suggests remedies
- Redundancy in parallel pumping systems keeps process running even if one pump fails
- Prevention of dry running and cavitation
- Coated boards for longer drive lifetime

Life cycle support

- Extensive support documentation and material
- Advanced PC tools available for dimensioning, programming, commissioning and maintenance
- Worldwide service network operated by ABB and its partners

What is an AC drive?

An AC drive is an electronic device that is used to adjust the rotating speed and torque of a standard, electric AC motor. The electric motor, in turn, drives a load such as a pump. An AC drive changes the frequency of the alternating current and voltage. A drive consists of three parts. A rectifier converts the input line power, which has a nominally fixed voltage and frequency, to fixed voltage DC power. This fixed voltage DC power is fed into the DC bus circuit, which filters the pulsating voltage. The inverter unit then changes the fixed voltage and frequency.



Built-in pump functions improve your efficiency

ACQ810 drives incorporate all the functions most commonly required by pump users. Pump specific features ensure accurate control of water flow throughout the processing cycle, from raw water, to utilization, to wastewater treatment.

Built-in pump specific features are easy to configure. Preconfigured macros for single and multi-pump applications walk you through drive setup. In addition, the built-in pump features can be easily customized to meet unique pump system configurations.

Soft pipe filling provides a pump with soft-start enabling a smooth build-up of flow in pipes. This avoids pressure peaks, for example in irrigation systems, where pipes are momentarily empty and controlled pipe filling is demanded. The life time of the pipe work and pumping system is increased.

Pump auto change balances the operating time of all the pumps in the parallel pumping system over the long term. The lifetime of the pumps and motors are increased. This helps to increase the mean time between repairs and reduce service costs.

Redundancy ensures reliable operation in multi-pump systems with several parallel pumps. The function provides system redundancy, so should one or more pumps fail or require maintenance, the remaining pumps continue operating. Overall maintenance time and cost are decreased.

Pump specific protections help to maintain disturbancefree operating time in a process. The protection functions indicate if the pre-defined process conditions change. If the flow or pressure exceeds defined process limits, the appropriate alarm is generated. For example, using this function can help prevent a pump dry run.



Remote monitoring and diagnostics for pumping stations can be easily implemented with ABB's SREA-01 Ethernet adapter. This optional remote interface module can send process data, logs and event messages independently, without additional on-site devices. The adapter's web server functionality brings remote monitoring interface to standard Internet browser. Routine site visits can be reduced helping to save costs. **Multi-pump control** is for applications where several parallel pumps are operated together and the required flow rate is variable. It maintains stable process conditions optimizing the speed and number of the pumps needed. This function provides the most energy efficient way to operate parallel pumps.



Pump priority is intended for systems where the consumption rate varies based on demand. For example, the drive can be programmed to operate higher capacity pumps during daytime and smaller units at night. This allows for better maintenance planning and can boost energy efficiency by operating pumps closer to their best efficiency point.

Sleep & boost is suitable for clean water pumping system, during night when water consumption falls. The drive's sleep & boost function detects pressure drops in the pipes and runs the pump to boost pressure prior to shutdown. Pumping restart when the pressure falls below the minimum level. This function extends the pump's sleep time and helps save energy. Also the lifetime of the pump and motor increase when non-productive running time is avoided.

Level control is used to control the filling or emptying of wastewater storage tanks. Fast-ramp starting creates a flush effect to keep pipes clear. In addition, users can define the "efficiency speed" based on the pumps best efficiency point. This helps to minimize overall energy consumption. Level control can be used within a station controlling up to eight pumps.

Pump cleaning or anti-jam is used in wastewater pumping stations to prevent pump and pipe clogging. A sequence of forward and reverse runs of the pump clean the impeller. If the pump cleaning function runs too often, an alarm is raised. The function can be timed to occur without interrupting the pumping duty cycle helping to maximize process uptime.

Inputs, outputs and dimensions

extensions



H = height W = width D = depth Mains connection 24 V DC input Relay outputs (2 x RO) Analog and digital 1111 Digital inputs (6 x DI) Digital inputs/outputs Н Analog inputs (2 x Al) Analog outputs (2 x AO) Modbus/drive-to-drive link Safe torque-off (STO) User interface C tools, control panel) Motor connection Removable memory unit

W

Smaller carbon footprint through improved energy efficiency

One of the biggest benefits of using ABB drives for water and wastewater applications is the energy saving opportunity over fixed speed or conventional flow control methods. Rather than have an electric motor running continuously at full speed, an AC drive allows the user to variably control the motor speed, depending on the demand.

ABB offers energy appraisals and energy saving tools for easily assessing energy savings in water and wastewater applications. Energy appraisals rapidly determine where and how much energy can be saved. Power savings of up to 50 percent can be reached by reducing the motor speed by just 20 percent. In addition, ABB drives offer a return on investment usually within two years based on energy saving alone.

A clean standard against polluted networks IEC/EN 61000-3-12

The ABB drives for water and wastewater applications fulfill IEC/EN 61000-3-12 and carry manufacturer's written statement of compliance. This means security and simplicity for specifying engineers and facility managers.

Dimensions

| Frame | Dimensions and weights | | | | | | | |
|-------------------|---------------------------|-------------------------|--------------|-------------------------|--|--|--|--|
| size | Height ¹⁾ | Depth 2) | Width | Weight | | | | |
| | mm | mm | mm | kg | | | | |
| A | 364 (518) | 219 | 94 | 3.2 | | | | |
| В | 380 (542) | 297 | 101 | 5.4 | | | | |
| С | 567 | 298 | 166 | 15.6 | | | | |
| D | 567 | 298 | 221 | 21.3 | | | | |
| E0 | 602 | 376 | 276 | 34 | | | | |
| E | 700 | 465 | 312 | 67 | | | | |
| G ³⁾ | 1564 | 571 | 562 | 200 | | | | |
| G1* ³⁾ | 1462 (1560) 4) | 505 (515) ⁴⁾ | 305 (329) 4) | 161 (191) ⁴⁾ | | | | |
| G2 ³⁾ | 1662 (1710) ⁴⁾ | 505 (515) ⁴⁾ | 305 (329) 4) | 199 (229) 4) | | | | |

Notes

All dimensions and weights are without additional options.

- Height is the maximum measure without clamping plates. In A and B frames the external C3 EMC-filter (height with filter in brackets). EMC-filter is internal in frames C, D, EO, E and G.
- ²⁾ Total depth with control panel ³⁾ G frames include separately mounted control section,
 - 325 mm H x 114 mm D x 94 mm W, 1.3 kg (except for frame G1 and G2 with integrated control unit)
- 4) With +H381 optional cabling panel

Technical data and types

Technical specification

| Mains connection | | | | |
|---|--|--|--|--|
| Voltage and power | 3-phase, 380 to 480 V, +10/-15% (1.1 to 500 kW) | | | |
| range | 3-phase, 200 to 240 V, +10/-10% (0.37 to 22 kW) | | | |
| Frequency | 50 to 60 Hz \pm 5% | | | |
| Motor connection | | | | |
| Motor types | Asynchronous AC induction motors | | | |
| Voltage | 3-phase, from 0 to $U_{\rm N}$ | | | |
| Output frequency | 0 to 500 Hz | | | |
| Motor control | ABB's DTC (direct torque control) | | | |
| Environmental limits | | | | |
| Degree of protection | IP20 according to EN 60529 (G frame IP00); | | | |
| Degree of protection | Open type according to UL 508 | | | |
| Ambient temperature | -10 to +55 °C, derating above 40 °C, no frost | | | |
| | allowed | | | |
| Installation altitude | 0 to 4000 m (IT network: 2000 m), derating | | | |
| | above 1000 m: 1%/100 m | | | |
| Polotivo humidity | | | | |
| Relative humidity | Max. 95%, no condensation allowed | | | |
| Contamination levels | According to IEC 60721-3-3: Chemical gases: | | | |
| | Class 3C2, Solid particles: Class 3S2, No conductive dust allowed | | | |
| In such a such as the term | | | | |
| Inputs and outputs | Calastable for auroration durally | | | |
| 2 analog inputs | Selectable for current and voltage | | | |
| Voltage signal | 0 to 10 V | | | |
| Current signal | 0 to 20 mA | | | |
| 2 analog outputs | 0 to 20 mA | | | |
| 2 bidirectional digital | 24 V logic levels, maximum 200 mA total output | | | |
| I/Os 6 digital inputs | current | | | |
| 6 digital inputs | 24 V logic levels | | | |
| 2 relay outputs | Maximum switching voltage 250 V AC/30 V DC, | | | |
| Madaua/Drivata driva | maximum continuous current 2 A rms | | | |
| Modbus/Drive to drive | Selectable, RS-485 serial link | | | |
| link | | | | |
| I/O extensions | Analog I/O extension, FIO-11 | | | |
| | Analog and digital I/O extension, FIO-21 | | | |
| | Relay extension, FIO-31 | | | |
| Communication options | DeviceNet™ adapter, FDNA-01 PROFIBUS DP adapter, FPBA-01 | | | |
| | Ethernet (EtherNet/IP™, Modbus/TCP), FENA-11 | | | |
| | Modbus adapter, FSCA-01 | | | |
| | LonWorks [®] adapter, FLON-01 | | | |
| Domoto monitoring | <u></u> | | | |
| Remote monitoring | Ethernet adapter, SREA-01 | | | |
| Protection functions | | | | |
| | Over/undervoltage controller | | | |
| | Motor short-circuit protection | | | |
| | Input phase-loss detection (both motor and line) | | | |
| | Overcurrent protection Drive temperature/overload controller | | | |
| | Power limits | | | |
| | Motor thermal protection | | | |
| Product compliance | | | | |
| | | | | |
| | CE dui LIL CSA GOST P CITICK | | | |
| Conformity to standards | CE, cUL, UL, CSA, GOST-R, C-Tick Frames G1 and G2: CE: pending: UL_GOST-R | | | |
| | Frames G1 and G2: CE; pending: UL, GOST-R, | | | |
| Conformity to standards | Frames G1 and G2: CE; pending: UL, GOST-R, cUL, CSA, C-Tick | | | |
| Conformity to standards Harmonics | Frames G1 and G2: CE; pending: UL, GOST-R, cUL, CSA, C-Tick IEC/EN 61000-3-12 | | | |
| Conformity to standards Harmonics EMC (according to | Frames G1 and G2: CE; pending: UL, GOST-R, cUL, CSA, C-Tick | | | |
| Conformity to standards Harmonics EMC (according to EN 61800-3) | Frames G1 and G2: CE; pending: UL, GOST-R, cUL, CSA, C-Tick IEC/EN 61000-3-12 Category C3 (C2 with optional filter) | | | |
| Conformity to standards Harmonics EMC (according to | Frames G1 and G2: CE; pending: UL, GOST-R, cUL, CSA, C-Tick IEC/EN 61000-3-12 Category C3 (C2 with optional filter) Safe torque-off (STO according to EN 61800-5-2) | | | |
| Conformity to standards Harmonics EMC (according to EN 61800-3) | Frames G1 and G2: CE; pending: UL, GOST-R, cUL, CSA, C-Tick IEC/EN 61000-3-12 Category C3 (C2 with optional filter) Safe torque-off (STO according to EN 61800-5-2) IEC 61508: SIL 3 | | | |
| Conformity to standards Harmonics EMC (according to EN 61800-3) | Frames G1 and G2: CE; pending: UL, GOST-R, cUL, CSA, C-Tick IEC/EN 61000-3-12 Category C3 (C2 with optional filter) Safe torque-off (STO according to EN 61800-5-2) IEC 61508: SIL 3 EN 62061: SILCL 3 | | | |
| Conformity to standards Harmonics EMC (according to EN 61800-3) Functional safety | Frames G1 and G2: CE; pending: UL, GOST-R, cUL, CSA, C-Tick IEC/EN 61000-3-12 Category C3 (C2 with optional filter) Safe torque-off (STO according to EN 61800-5-2) IEC 61508: SIL 3 | | | |
| Conformity to standards Harmonics EMC (according to EN 61800-3) Functional safety PC tools | Frames G1 and G2: CE; pending: UL, GOST-R, cUL, CSA, C-Tick IEC/EN 61000-3-12 Category C3 (C2 with optional filter) Safe torque-off (STO according to EN 61800-5-2) IEC 61508: SIL 3 EN 62061: SILCL 3 EN ISO 13849-1: PL e | | | |
| Conformity to standards Harmonics EMC (according to EN 61800-3) Functional safety | Frames G1 and G2: CE; pending: UL, GOST-R, cUL, CSA, C-Tick IEC/EN 61000-3-12 Category C3 (C2 with optional filter) Safe torque-off (STO according to EN 61800-5-2) IEC 61508: SIL 3 EN 62061: SILCL 3 | | | |

Types and ratings

| P _N (kW) | | 1 _{2N} | I _{cont} | I _{max} | Type designation | Frame |
|---------------------|--------------------|-----------------|-------------------|------------------|---------------------|-------|
| | | (A) | (A) | (A) | (order code) | size |
| $U_{\rm N}$ =400 V | $U_{\rm N}$ =230 V | . , | | | | |
| 1.1 | 0.37 | 2.7 | 3 | 4.4 | ACQ810-04-02A7-4/2* | А |
| 1.1 | - | 3 | 3.6 | 5.3 | ACQ810-04-03A0-4 | A |
| 1.5 | 0.55 | 3.5 | 4.8 | 7.0 | ACQ810-04-03A5-4/2* | A |
| 2.2 | 0.75 | 4.9 | 6 | 8.8 | ACQ810-04-04A9-4/2* | A |
| 3 | 1.1 | 6.3 | 8 | 10.5 | ACQ810-04-06A3-4/2* | A |
| 4 | 1.5 | 8.3 | 10.5 | 13.5 | ACQ810-04-08A3-4/2* | В |
| 5.5 | 2.2 | 11 | 14 | 16.5 | ACQ810-04-11A0-4/2* | В |
| 7.5 | 3 | 14.4 | 18 | 21 | ACQ810-04-14A4-4/2* | В |
| 11 | 5.5 | 21 | 25 | 33 | ACQ810-04-021A-4/2* | С |
| 15 | 7.5 | 28 | 30 | 36 | ACQ810-04-028A-4/2* | С |
| 18.5 | - | 35 | 44 | 53 | ACQ810-04-035A-4 | С |
| 22 | 11 | 40 | 50 | 66 | ACQ810-04-040A-4/2* | С |
| 30 | 15 | 53 | 61 | 78 | ACQ810-04-053A-4/2* | D |
| 37 | 18.5 | 67 | 78 | 100 | ACQ810-04-067A-4/2* | D |
| 45 | 22 | 80 | 94 | 124 | ACQ810-04-080A-4/2* | D |
| 55 | - | 98 | 103 | 138 | ACQ810-04-098A-4 | E0 |
| 75 | _ | 138 | 144 | 170 | ACQ810-04-138A-4 | E0 |
| 90 | - | 162 | 202 | 282 | ACQ810-04-162A-4 | E |
| 110 | — | 203 | 225 | 326 | ACQ810-04-203A-4 | E |
| 132 | - | 240 | 260 | 326 | ACQ810-04-240A-4 | E |
| 160 | - | 286 | 290 | 348 | ACQ810-04-286A-4 | E |
| 160 | - | 302 | 340 | 480 | ACQ810-04-302A-4 | G |
| 160 | - | 361 | 400 | 568 | ACQ810-04-361A-4 | G |
| 200 | - | 414 | 430 | 588 | ACQ810-04-414A-4 | G |
| 250 | _ | 477 | 521 | 588 | ACQ810-04-477A-4 | G |
| 315 | _ | 550 | 602 | 840 | ACQ810-04-550A-4 | G |
| 355 | - | 616 | 693 | 1017 | ACQ810-04-616A-4 | G |
| 400 | - | 704 | 720 | 1017 | ACQ810-04-704A-4 | G |
| 200 | _ | 377 | 387 | 470 | ACQ810-04-377A-4 | G1 |
| 250 | - | 480 | 500 | 560 | ACQ810-04-480A-4 | G1 |
| 315 | - | 570 | 580 | 680 | ACQ810-04-570A-4 | G1 |
| 355 | - | 634 | 650 | 730 | ACQ810-04-634A-4 | G1 |
| 400 | _ | 700 | 710 | 850 | ACQ810-04-700A-4 | G2 |
| 450 | _ | 785 | 807 | 1020 | ACQ810-04-785A-4 | G2 |
| 500 | | 857 | 875 | 1100 | ACQ810-04-857A-4 | G2 |

 $P_{\rm N}\,$ = Typical motor power $I_{\rm 2N}\,$ = 110% overload allowed for 1 minute every 5 minutes through the entire speed range

 $I_{cont} =$ Continuous output current with no overload capacity $I_{max} =$ Maximum output current. Available for 10 s at start, otherwise as long as allowed by drive temperature.

 * The last number in type code (4 or 2) refers nominal supply voltage $U_{\rm \tiny N}$ Select number 4 when $U_{\rm N}$ is 400 V and number 2 when $U_{\rm N}$ is 230 V.

Note: The ratings apply at 40 °C ambient temperature



Contact us

For more information please contact your local ABB representative or visit:

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